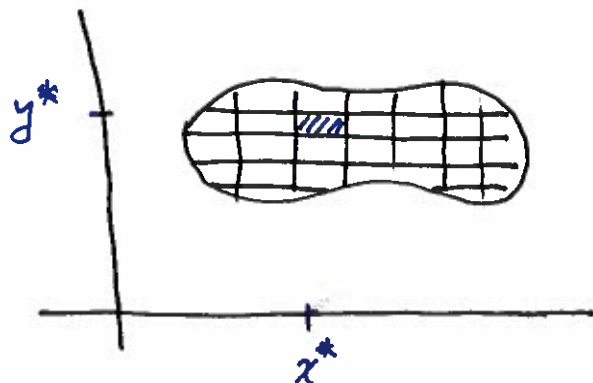


§15.5 Applications of Double Integrals

Center of Mass



~~the~~ little piece of mass at (x^*, y^*)

Small piece of mass = (density)(small area)

$$dm = \rho(x, y) dA$$

first moments = (mass)(distance)

about x-axis:

$$dM_x = y dm$$

about y-axis:

$$dM_y = x dm$$

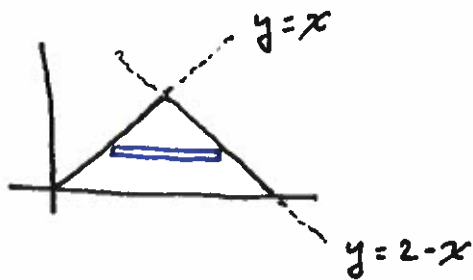
Integrate to get m , M_x , M_y and then the center of mass is

$$(\bar{x}, \bar{y}) = \left(\frac{M_y}{m}, \frac{M_x}{m} \right)$$

Note that centroid is when $\rho(x, y) = 1$

Examples Find the center of mass

(i)



bounded by x -axis, $y=x$
and $y=2-x$, with $\rho(x,y)=xy$

This region is y -simple, but not x -simple.
The intersection of $y=x$ and $y=2-x$ is $(1,1)$.
So

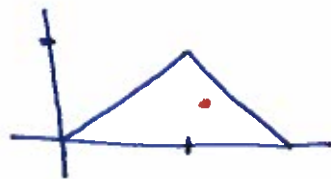
$$dm = xy \, dx \, dy$$

$$m = \int_0^1 \int_y^{2-y} xy \, dx \, dy \stackrel{\text{CAS}}{=} \frac{1}{3}$$

$$M_x = \int_0^1 \int_y^{2-y} xy^2 \, dx \, dy \stackrel{\text{CAS}}{=} \frac{1}{6}$$

$$M_y = \int_0^1 \int_y^{2-y} x^2 y \, dx \, dy \stackrel{\text{CAS}}{=} \frac{11}{60}$$

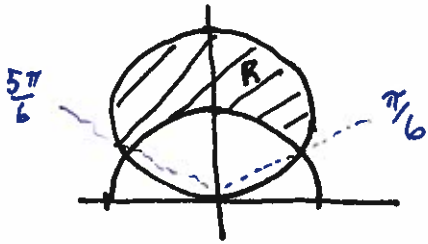
$$\text{So } \bar{x} = \frac{M_y}{m} \stackrel{\text{CAS}}{=} \frac{11}{10} = 1.1, \quad \bar{y} = \frac{M_x}{m} = \frac{1}{2} = .5$$



seems reasonable

Example Find the centroid

(ii)



In polar
 Inside $x^2 + (y-1)^2 = 1 \Leftrightarrow r = 2\sin(\theta)$
 Outside $x^2 + y^2 = 1 \Leftrightarrow r = 1$

$$\begin{aligned} &\downarrow \\ &1 = 2\sin(\theta) \\ &\sin(\theta) = \frac{1}{2} \\ &\theta = \frac{\pi}{6}, \frac{5\pi}{6} \end{aligned}$$

$$\begin{aligned} m &= \iint_R dA = \int_{\pi/6}^{5\pi/6} \int_1^{2\sin(\theta)} r \, dr \, d\theta \\ M_x &= \iint_R y \, dA = \int_{\pi/6}^{5\pi/6} \int_1^{2\sin(\theta)} r \sin(\theta) \cdot r \, dr \, d\theta \\ M_y &= \iint_R x \, dA = \int_{\pi/6}^{5\pi/6} \int_1^{2\sin(\theta)} r \cos(\theta) \cdot r \, dr \, d\theta \end{aligned}$$

Using Mathematica we get

$$m = \frac{3\sqrt{3} + 2\pi}{6}, \quad M_x = \frac{3\sqrt{3} + 8\pi}{12}, \quad M_y = 0$$

Note $M_y = 0$ by symmetry could have been determined by the picture.

So

$$\bar{x} = 0, \quad \bar{y} \approx 1.321$$

which seems reasonable.

Moment of Inertia (Second Moments)

This is a concept that is used in angular "stuff"

Moment of Inertia = (mass)(distance squared)

2nd Moment about x-axis:

$$I_x = \iint_R y^2 dm$$

2nd Moment about y-axis:

$$I_y = \iint_R x^2 dm$$

Most used: 2nd Moment about the origin

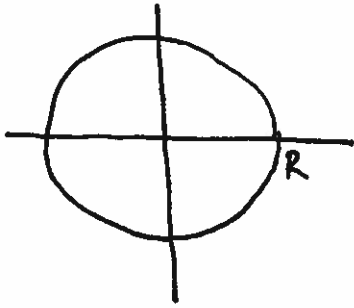
$$I_o = \iint_R (x^2 + y^2) dm$$

Radius of gyration about an axis (point)

$$m R^2 = I \Leftrightarrow R = \sqrt{\frac{I}{m}}$$

Example Radius of gyration of a solid wheel.

(iii) Consider the solid disk of density 1 and radius R .



the total mass = area

$$m = \pi R^2$$

The 2nd moment about the origin in polar coordinates is

$$I_0 = \iint_R (x^2 + y^2) dm = \int_0^{2\pi} \int_0^R r^2 \cdot r dr d\theta$$

$$= 2\pi \left(\frac{1}{4} r^4 \Big|_0^R \right)$$

$$= \frac{\pi R^4}{2}$$

So the radius of gyration about the origin is

$$\text{R.O.G.} = \sqrt{\frac{\pi R^4}{2} \div \pi R^2} = \frac{R}{\sqrt{2}}$$

That is, the disk has the same angular physics behavior as a "perfect" bicycle wheel of radius $\frac{R}{\sqrt{2}}$ and the same total mass.